MyoBack: A Musculoskeletal Model of the Human Back with Integrated Exoskeleton

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Digital Twins of <u>Back Models</u> are important in:

- Understanding full body motion (e.g. walking, balancing, squatting.)
- Development and testing of assistive devices Modeling back-related MSK disorders









Step 1: MyoBack Conversion and Finetuning

- 1. Selecting an available OpenSim model
- 2. Converting to MyoSuite compatible version using MyoConverter (Wang et al. 2022)
- 3. Fixing and Finetuning
 - Muscle jumping
 - Immobile abdomen
 - Non-curved spine
 - Absent thoracic vertebrae
- 4. Validating against kinematic readings in:





Step 3: Validation against Human Experiment

 \geq 9 participants (height in cm: 173.8 ± 11.1, weight in kg: 73.4) \pm 16.5, age in years: 23.5 \pm 1.4)



Step 2: Creating a digital Twin of Auxivo ExoSuit

- 1. Modeling elastic bands as tendon in MuJoCo
 - \succ K_{Auxivo} = F/ Δ L = 1527.5N/m
 - \succ K_{MuJoCo} = 526.4N/m due to different length
- Deciding Attachment Point:
 - the level of the 5th thoracic rib
 - > the posterior superior iliac spine
- Creating wrapping object (cylinder) 3.



Step 4: Reinforcement Learning and MyoBack

- Compatible with Gymnasium RL framework
- Significant reduction in metabolic cost using Exosuit
- Stoop at four different flex-extension angles

Metabolic Cost of Stooping at Various Angles with and without Exosuit



✓ Without Exosuit ■ With Exosuit



Looking Beyond

- Integration with lower limb MSK model **
- Coordination with active Back Exoskeleton •••
- Understanding and modeling of *Lower Back* • Pain (LBP) and other MSK disorder

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Open Source and Fully Available @myo_sim and @MyoSuite!

